

ELEMENTI di CALCOLO delle VARIAZIONI

LEZIONE 2 - 1.10.2024

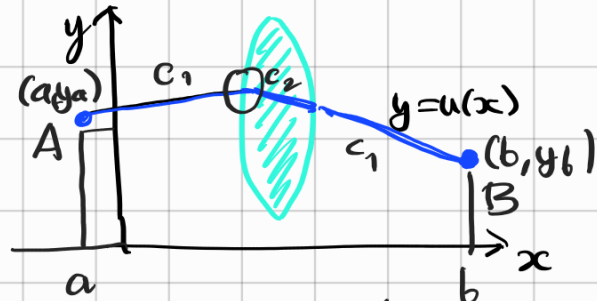
$$I(u) = \int_a^b L(x, u(x), u'(x)) dx \rightarrow \min$$

$$E-L: \quad \frac{\partial L}{\partial y}(x, u(x), u'(x)) = \frac{d}{dx} \frac{\partial L}{\partial z}(x, u(x), u'(x))$$

Esempio il problema di Fermat

$$I(u) = \int_a^b g(x, u(x)) \cdot \sqrt{1+(u'(x))^2} dx$$

$$\begin{cases} I(u) \rightarrow \min \\ u(a) = y_a, u(b) = y_b \end{cases}$$



$$g(x, y) = \frac{1}{c(x, y)}$$

$$I(u) = \int_a^b L(x, u(x), u'(x)) dx \quad \text{con} \quad L(x, y, z) = g(x, y) \cdot \sqrt{1+z^2}$$

$$\frac{\partial L}{\partial y} = \frac{\partial g}{\partial y} \cdot \sqrt{1+z^2}$$

$$\frac{\partial L}{\partial z} = g \cdot \frac{z}{\sqrt{1+z^2}}$$

$$E-L: \quad \frac{\partial L}{\partial y} = \frac{d}{dx} \frac{\partial L}{\partial z}$$

$$\frac{\partial g}{\partial y}(x, u(x)) \cdot \sqrt{1+(u'(x))^2} = \frac{d}{dx} \left(g(x, u(x)) \cdot \frac{u'(x)}{\sqrt{1+(u'(x))^2}} \right)$$

$$\textcircled{1} \text{ Dove } g \text{ \u00e9 costante: } \quad 0 = g(x, u(x)) \cdot \frac{d}{dx} \frac{u'(x)}{\sqrt{1+(u'(x))^2}}$$

$$g \neq 0 \Rightarrow \frac{d}{dx} \frac{u'(x)}{\sqrt{1+(u'(x))^2}} = 0$$

curvatura

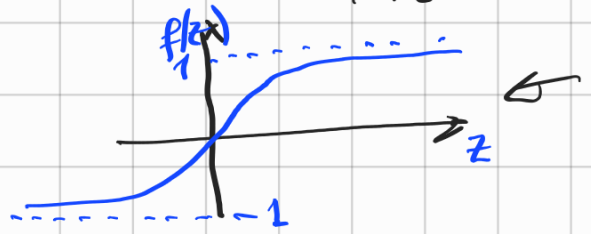
$$f(z) = \frac{u'(x)}{\sqrt{1+(u'(x))^2}} = \text{costante}$$

$$\left[\begin{aligned} f'(z) &= \frac{\sqrt{1+z^2} - z \frac{z}{\sqrt{1+z^2}}}{1+z^2} \\ &= \frac{1+z^2 - z^2}{\sqrt{1+z^2}(1+z^2)} > 0 \end{aligned} \right.$$

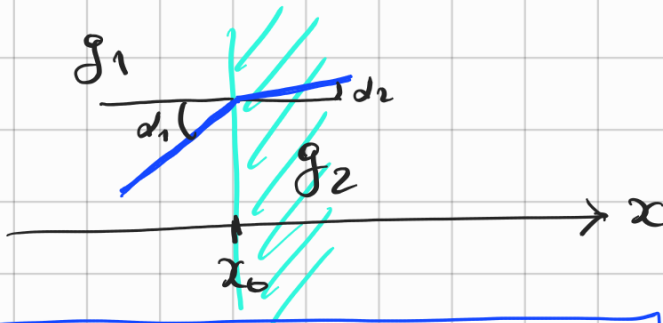
$$\Rightarrow u'(x) = m \text{ costante}$$

$$u(x) = mx + q.$$

$$f(z) = \frac{z}{\sqrt{1+z^2}}$$

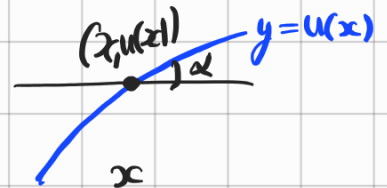


② Sulla superficie della lente



E.L.

$$\frac{\partial g}{\partial y} \cdot \sqrt{1+u'^2} = \frac{d}{dx} \left(g \cdot \frac{u'}{\sqrt{1+u'^2}} \right)$$



$$g(x,y) = g(x)$$

↑
IPOTESI

$$\frac{u'}{\sqrt{1+u'^2}} = \sin \alpha(x)$$

$$u'(x) = \tan \alpha$$

$$\sqrt{1+u'^2} = \sqrt{1+\tan^2 \alpha} = \frac{1}{\cos \alpha}$$

$$1+\tan^2 \alpha = 1 + \frac{\sin^2 \alpha}{\cos^2 \alpha} = \frac{\cos^2 \alpha + \sin^2 \alpha}{\cos^2 \alpha}$$

$$\cos^2 \alpha = \frac{1}{1+\tan^2 \alpha}$$

$$\sin^2 \alpha = \frac{1+\tan^2 \alpha - 1}{1+\tan^2 \alpha} = \frac{\tan^2 \alpha}{1+\tan^2 \alpha}$$

$$\sin \alpha = \frac{\tan \alpha}{\sqrt{1+\tan^2 \alpha}}$$

$$g(x) - \sin \alpha(x) = \text{costante}$$

$$g_1 \sin \alpha_1 = g_2 \sin \alpha_2$$

$$\frac{\sin \alpha_1}{\sin \alpha_2} = \frac{g_2}{g_1} = \frac{c_1}{c_2}$$

LEGGE DI
SNELL

$\alpha_1 =$ angolo di incidenza

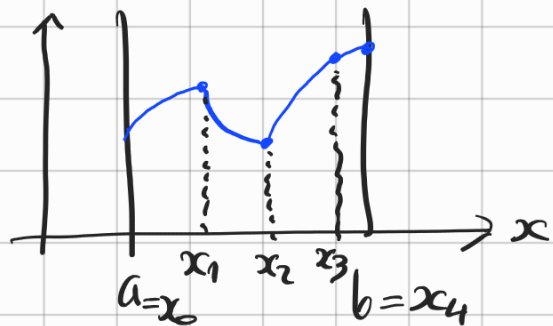
$\alpha_2 =$ angolo di rifrazione.

Def $u \in C^1$ a pezzi $u \in C_p^1([a,b])$ se

(1) $u \in C^0([a,b])$

(2) esistono $n-1$ punti:

$$a = x_0 < x_1 < \dots < x_n = b$$



$$u \in C^1([x_k, x_{k+1}]) \quad k=0, \dots, n-1.$$

$$I(u) = \sum_{k=0}^{n-1} \int_{x_k}^{x_{k+1}} L(x, u(x), u'(x)) dx$$

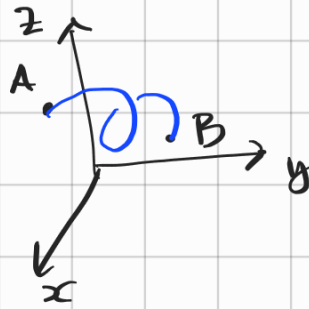
ha senso!



Sempre Fermat ma con le curve

$$\underline{u} : [a, b] \rightarrow \mathbb{R}^n$$

$$x \mapsto \underline{u}(x)$$



$$\mathcal{L}(\underline{u}) = \int_a^b g(\underline{u}(x)) \cdot \underbrace{|\underline{u}'(x)|}_{ds} dx$$

$$\begin{cases} \mathcal{L}(\underline{u}) \rightarrow \min \\ \underline{u}(a) = A \\ \underline{u}(b) = B \end{cases}$$

$$L(x, \underline{y}, \underline{z}) = g(\underline{y}) \cdot |\underline{z}|$$

IN GENERALE

$$\mathcal{L}(\underline{u}) = \int_a^b L(x, \underline{u}(x), \underline{u}'(x)) dx$$

$$L : [a, b] \times \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$$

$$(x, \underline{y}, \underline{z}) \mapsto L(x, \underline{y}, \underline{z})$$

So \underline{u} è un minimo:

$$\forall \varphi \in C_0^1([a, b], \mathbb{R}^n)$$

$$0 = \frac{d}{d\varepsilon} \mathcal{L}(\underline{u} + \varepsilon \varphi) \Big|_{\varepsilon=0} = \int_a^b \frac{d}{d\varepsilon} L(x, \underbrace{\underline{u} + \varepsilon \varphi}_{\underline{y}_1 \dots \underline{y}_n}, \underbrace{\varphi' + \varepsilon \varphi'}_{\underline{z}_1 \dots \underline{z}_n}) dx$$

$$= \int_a^b \left[\sum_{k=1}^n \frac{\partial L}{\partial y_k}(x, \underline{u}, \underline{u}') \varphi_k(x) + \sum_{k=1}^n \frac{\partial L}{\partial z_k}(x, \underline{u}, \underline{u}') \varphi_k'(x) \right] dx$$

$$= \int_a^b \left[\nabla_{\underline{y}} L(x, \underline{u}, \underline{u}') \cdot \underline{\varphi} + \nabla_{\underline{z}} L(x, \underline{u}, \underline{u}') \cdot \underline{\varphi}'(x) \right] dx$$

$$= \int_a^b \left[\nabla_{\underline{y}} L(x, \underline{u}, \underline{u}') - \frac{d}{dx} \nabla_{\underline{z}} L(x, \underline{u}, \underline{u}') \right] \cdot \underline{\varphi}(x) dx$$

$$+ \left[\nabla_{\underline{z}} L(x, \underline{u}, \underline{u}') \cdot \underline{\varphi}(x) \right]_a^b$$

$$(\varphi(a) = 0, \varphi(b) = 0)$$

Se prendo $\underline{q} = \begin{pmatrix} 0 \\ \vdots \\ q_k \\ \vdots \\ 0 \end{pmatrix}$ $0 = \int [\nabla_y L - \frac{d}{dx} \nabla_z L]_k \cdot q_k$

$\forall q_k$

$\Rightarrow \nabla_y L - \frac{d}{dx} \nabla_z L = 0$

E-L: $\nabla_y L(x, \underline{u}, \underline{u}') = \frac{d}{dx} \nabla_z L(x, \underline{u}, \underline{u}')$
 VETTORIALE

Torniamo a Fermat:

$L(x, \underline{y}, \underline{z}) = g(\underline{y}) \cdot |\underline{z}|$

$\nabla_y L = \nabla g(\underline{y}) \cdot |\underline{z}|$

$\nabla_z L = g(\underline{y}) \cdot \frac{\underline{z}}{|\underline{z}|}$

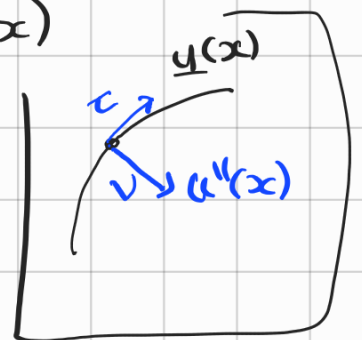
E-L: $\nabla g(\underline{u}(x)) \cdot |u'(x)| = \frac{d}{dx} \left(g(\underline{u}(x)) \cdot \frac{u'(x)}{|u'(x)|} \right)$
 $= \left(\nabla g(\underline{u}) \cdot \underline{u}'(x) \right) \frac{u'(x)}{|u'(x)|} + g(u) \cdot \frac{d}{dx} \frac{u'(x)}{|u'(x)|}$

Supponiamo: $|u'(x)| = 1$ (riparametrizzo con
 $u'(x) = \tau$ lunghezza d'arco)

$\nabla g(\underline{u}) = (\nabla g \cdot \tau) \tau + g(u) \cdot \underline{u}''(x)$

$|u'(x)|^2 = 1$

$0 = \frac{d}{dx} (u'(x))^2 = 2 u'(x) \cdot u''(x)$
 $u''(x) \perp u'(x)$

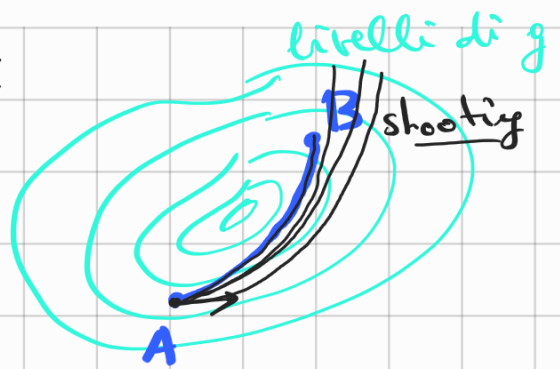


$\underline{u}''(x) = k \cdot \underline{v}$

$\nabla g(\underline{u}) = (\nabla g \cdot \tau) \tau + k g(u) \cdot \underline{v}$

Prodotto scalare con \underline{v} :

$$\frac{\partial g}{\partial \underline{v}} = k \cdot g(u)$$



EQUAZIONE DI BELTRAMI

$$L(x, y, z) = L(y, z)$$

$$I(u) = \int_a^b L(u(x), u'(x)) dx$$

$$E-L: \quad \frac{\partial L}{\partial y}(u(x), u'(x)) = \frac{d}{dx} \frac{\partial L}{\partial z}(u(x), u'(x))$$

EQ. differenziale del secondo ordine, autonoma

Moltiplico tutto per $u'(x)$

(non dipende da x)

$$u' \cdot \frac{\partial L}{\partial y}(u, u') = u' \frac{d}{dx} \frac{\partial L}{\partial z}(u, u')$$

$$\frac{d}{dx} L(u, u') = \frac{\partial L}{\partial y} \cdot u' + \frac{\partial L}{\partial z} \cdot u''$$

$$= u' \frac{d}{dx} \frac{\partial L}{\partial z} + \frac{\partial L}{\partial z} u''$$

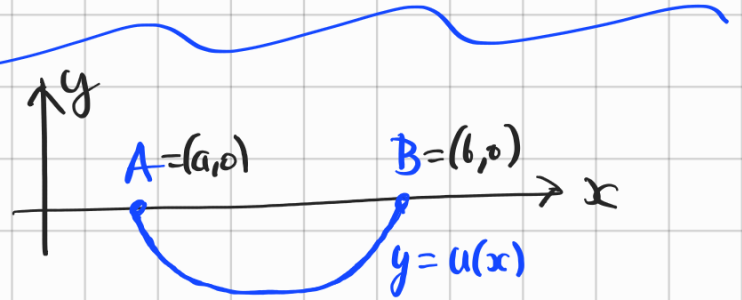
$$= \frac{d}{dx} \left(u' \cdot \frac{\partial L}{\partial z} \right)$$

$$\frac{d}{dx} \left(L - u' \frac{\partial L}{\partial z} \right) = 0$$

$$L - u' \frac{\partial L}{\partial z} = \text{cost.}$$

EQ. di BELTRAMI.

CATENARIA



La catena minimizza l'energia potenziale:

$$I(u) = \int_a^b u(x) \sqrt{1 + (u'(x))^2} dx$$

$$u: [a, b] \rightarrow \mathbb{R}$$

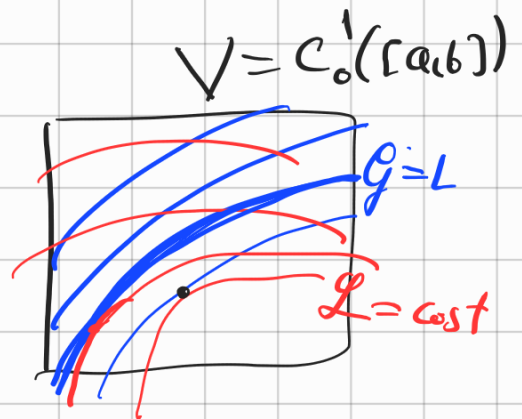
$$u(a) = 0$$

$$u(b) = 0$$

è un problema vincolato:

$$G(u) = \int_a^b \sqrt{1 + (u'(x))^2} dx$$

$$\begin{cases} I(u) \rightarrow \min \\ G(u) = L \\ u(a) = u(b) = 0 \end{cases}$$



Moltiplicatori di Lagrange: " $\nabla I = \lambda \nabla G$ "

CONTINUA NELLA PROSSIMA LEZIONE